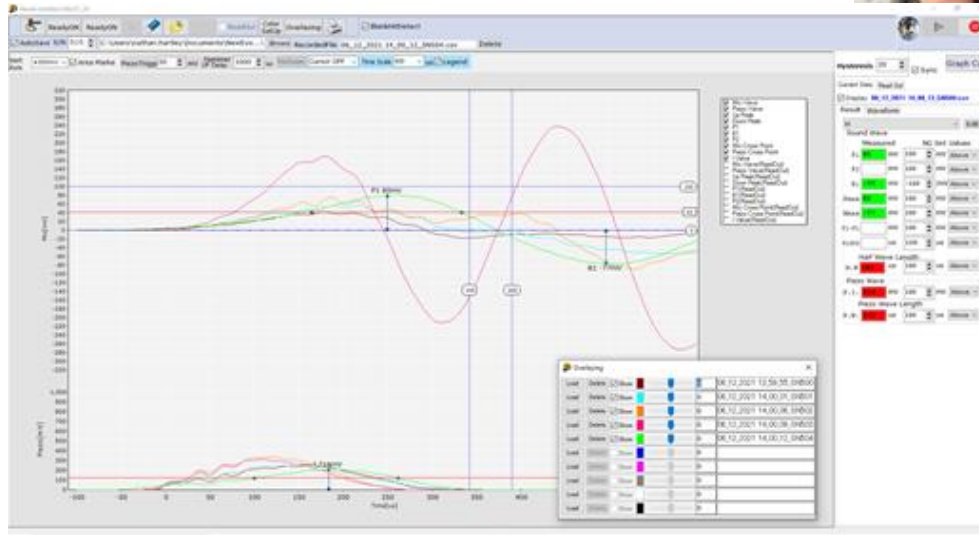




- Advanced Tap Tester using acoustic analysis method
- Two sensors (Piezo crystal and microphone) are used to capture responses from solenoid driven tapping device
- Software allows point measurements to be compared
- Potential to integrate with probe tracking and visualisation software



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Features:

- Monitoring of acoustic response (microphone) & feedback from piezoelectric crystal integrated in the actuator
- Easy operation
- ON line mode:
 - Quantitive & graphical display in real time
 - Logging of values (export to Excel)
- OFF line mode
 - Export to .csv file for analysis
- Different frequency settings
- Examination possible in noisy environments

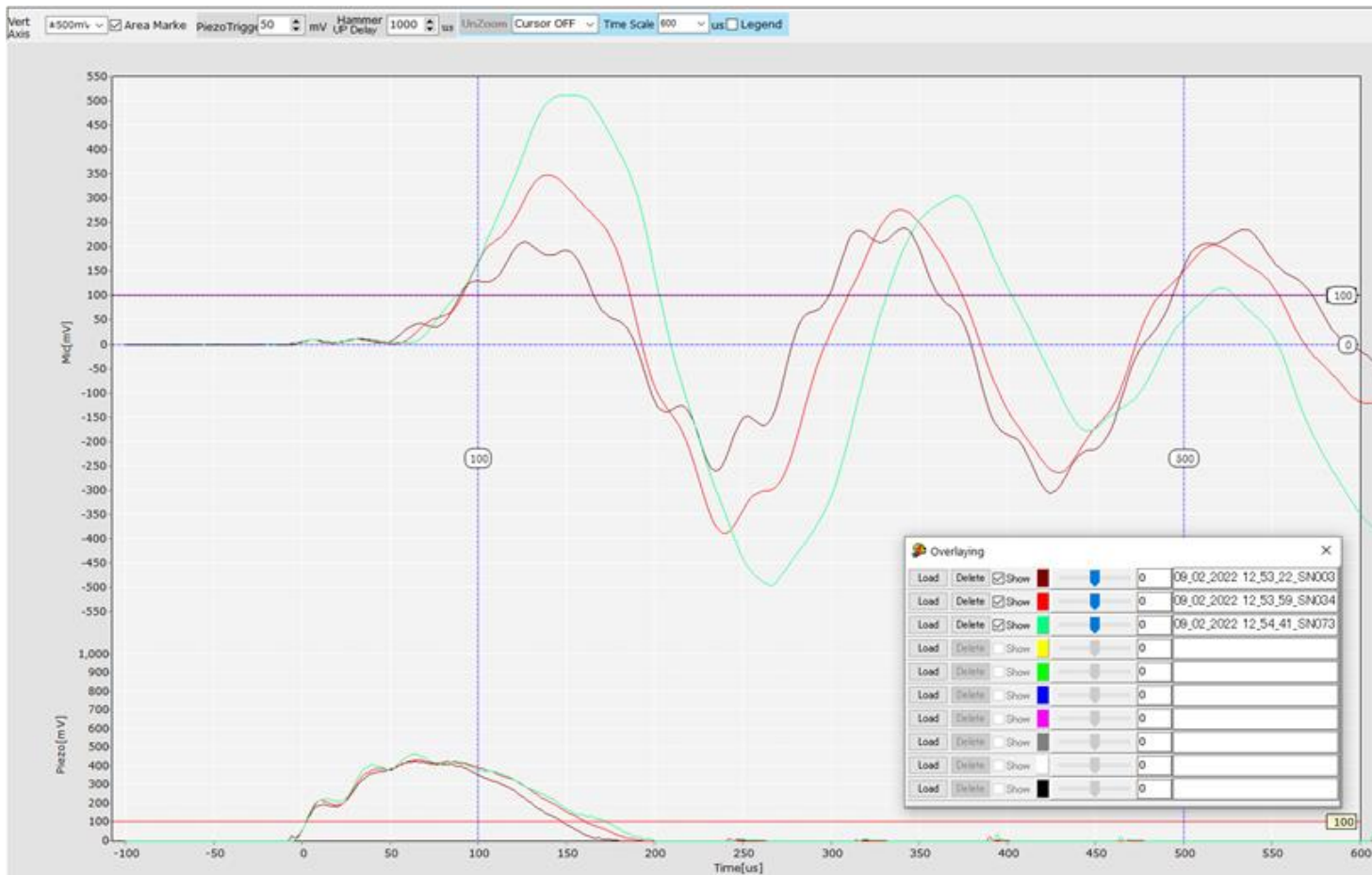


Applications:

- Detection in: thick structural components (30 mm+)
- Detection of inserts & changes in structure
- Marine: inspection of bonded parts to include bulkheads, beams, hull/deck bond; currently being used to revalidate legacy lifeboats
- Offshore: inspection of skins, ribs & spar bonds to include lightning strike parameters of damage
- Civil: inspection for voids, ceramic tile bonds, material levels behind shuttering, concrete cancer, moisture damage



Typical EVOTIS software display



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WHAT'S IN THE BOX?



CD with
software

4 x AA
Batteries

Cables &
replacement
parts

Evotis Probe

4 x AA
Battery Pack

Evotis Control
Box



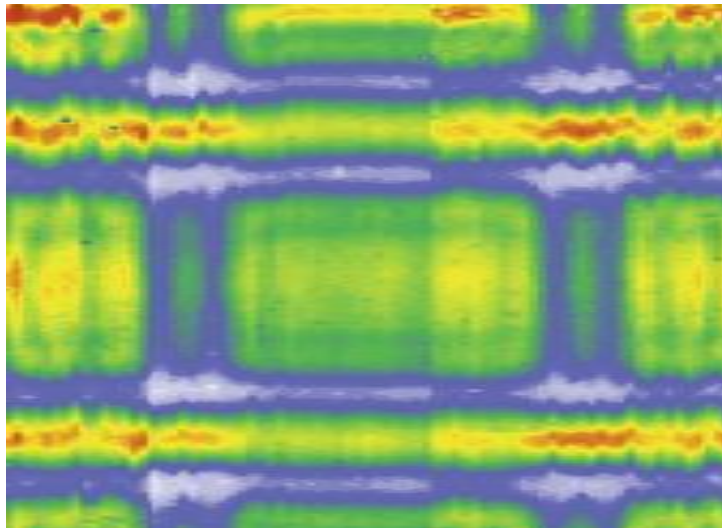
Specification:

- Handheld device to be used in real time with a PC/laptop
- Size (mm) : H100 × W230 × L190
- Weight (Kg) : 2
- Power : 4 x AA batteries; life about 5 hours
- Monitoring of acoustic response (microphone) & feedback from piezoelectric crystal integrated in the actuator
- Optional probe tracking & visualization (3D) software



Optional Probe Tracking and Visualisation Software

TWI have developed an automated tap-test system based on a modified Evotis unit & bespoke software for data acquisition, signal processing & visualisation



The system allows inspection of large areas, including complex GFRP structures. The software automatically tracks the position of the probe & records the responses from the unit, digitally processes them & displays the results in the familiar “heat map” or c-scan type format

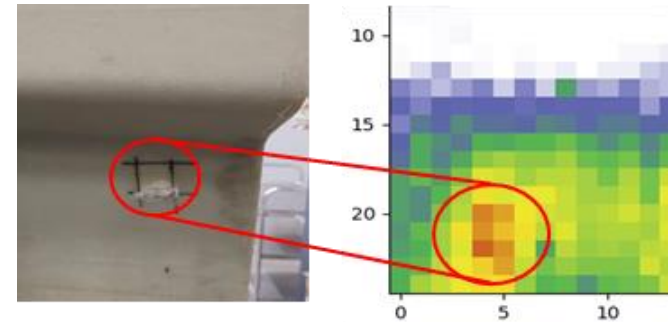
Typical results from a large area scan

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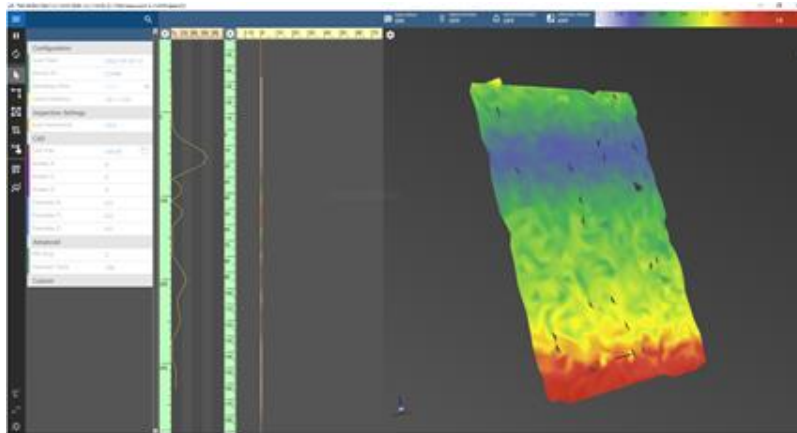




The system has been trialled on a number of structures including very thick GFRP laminates such as wind turbine blades & complex structural geometries like boat hulls, with excellent results



Artificial defect and inspection results for GFRP structure



Screenshot from TWI's 3D data acquisition and visualisation software, showing data obtained from robotic tap testing prototype

Fully automated inspection enable 3D visualisation of the results, overlaid onto a CAD model of the structure. This allows easy interpretation and analysis of the results and mapping of defects, anomalies and indications for lifetime records and future reference

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Large area mapping
utilising a number of
integrated options for
example: co-bot, crawler
or encoder



HausBot HB1 Crawler Robot



Evotis tap tester mounted on a UR10e Collaborative Robot for automated inspection of a large GFRP sample

TWI licence the software & offer the
training package - PAO

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